T ROTATING TORQUE METER





Compact design suitable for installation in equipment — Contactless torque meter for automation of torque control

Rotating torque meter, UTM II, designed with Unipulse's improved unique torque sensing technology! Suitable for installing in small confined space of machines which were not possible in the past.

- Available in 17 different capacity ranging from 0.05Nm to 10000Nm.
- Cut-off frequency of 1kHz with high-speed sampling at 6kHz.
- Suitable for torque ripple measurement
- Safe overload of 500%
- Power supply DC24V

Compact and easy to install

The six models (0.05, 0.1, 0.2, 0.5, 1, 2Nm) are particularly compact and light: 54Wx50Hx40Dmm in size, 200g or less in weight.

Maintenance-free

No slip-ring.

The lifetime of UTMII is mainly determined by the lifetime of bearings.

Max. rotational speed 25000rpm

0.05 to 10Nm	25000rpm
20、50Nm	20000rpm
100Nm	15000rpm
200Nm	12000rpm
500Nm	10000rpm
1000Nm	7000rpm
2000Nm	6000rpm
5000Nm	5000rpm
10000Nm	4000rpm

- No external amplification required: ±5V analog output voltage
- A rotational pulse generating circuit (4 pulses/revolution) is built in as standard.
- Improved noise immunity with insulated powering and signaling system.

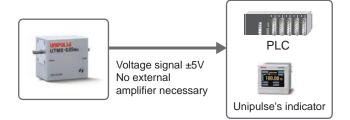
High accuracy and stability

1/10000 resolution with outstanding zero stability. UTMII accurately measures tiny torque variations.

Small starting torque

The starting torque of the bearing in the UTMII-0.05Nm is only 0.00001Nm (0.03 %FS). Actually, the effect of rotating friction can be negligible.

Smart system configuration with no external circuits needed



Indicators for UTM II

Easy connection to UTMI just by using a snap-on cable.

■ TM301:basic type
Torque, rotation speed,
and power are displayed
simultaneously.



■TM400:portable type Torque vs. rotation speed / torque-angle waveform can be monitored.



■ TM700:graphic monitor with high sampling speed Torque, rotation speed and power are measured at 20kHz sampling rate.



■ TM500:angle monitor Toque vs. Angle curve" is monitored. (Designed for UTMII encoder option)



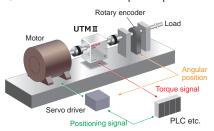
■TM201:for R&D and laboratory use

A USB interface converter for UTM $\rm II$. Torque, rotation speed and power are monitored on PC.

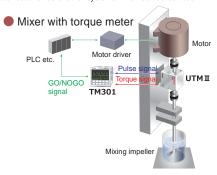


Measurement of dynamic/running torque

Servo-motor with torque output



By setting UTM ${\rm I\hspace{-.1em}I}$ between the rotary encoder and motor, you can make a servo motor system with torque output.
The system can be applied to various applications, such as robot hands or other systems which can detect load.



The system measures torque on the axis of mixing impellers. The change of viscosity can be detected by monitoring torque.

By using TM301, I/O signals can be controlled by the threshold levels.



Torque fluctuation can be monitored while a sheet of paper or film is fed by the drive roller.

With torque measurement, quantitative management and maintenance of feed roller are possible.

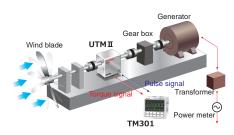
Motor test bench



Mechanical power can be calculated from torque and rotational speed.

Also, by applying energy recovery system, the test apparatus will be eco-friendly (energy-saving).

Power generation efficiency test



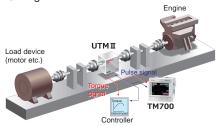
The efficiency of wind turbine generator and so on can be tested. Power can be estimated based on torque and rotational speed measured with UTM II. and power generation efficiency can be calculated by comparing power and generated energy.

Quality inspection of steering unit



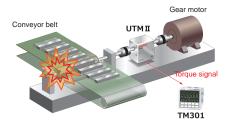
By measuring the torque required to rotate automotive parts such as steering unit, it is possible to quantize the smoothness of the rotation for standardization of the quality inspection

Engine test bench



In case of torque measurement with large vibration, such as measurement of engines, please attach double disk coupling and use double bearing.

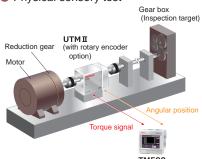
Fault detection of conveyor belt



By monitoring the motor shaft torque of a conveyor belt. faults and conveyor-related hazards can be detected (e.g. materials get caught to conveyor system). Conveyor belts will be stopped immediately after faults like contamination and overturning of products are detected.

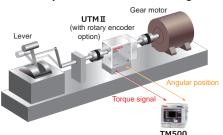
Relationship between torque and angle/displacement (distance)

Physical sensory test



Torque corresponding to angular position can be monitored by using UTM ${\mathbb I}$ with rotary encoder option. The system can be applied to automation of physical

Sensory evaluation of lever or hinge

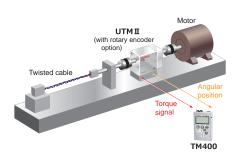


Screw driver with torque monitoring



Torque can be measured in the process of tightening screws. Since the torque can be controlled during the whole process, the system can be applied to automation of process.

Torsion testing machine



Stiffness and performance of wire or cable can be tested by checking torque applied by a torsion test machine with UTM II.

Smoothness of lever, hinge, and so on can be quantized for quality control purpose.

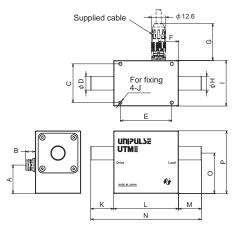
With a optional rotary encoder, torque-angle relationship

Specifications

Measuren	nent range	0.05Nm	0.1Nm	0.2Nm	0.5Nm	1Nm	2Nm	5Nm	10Nm	20Nm	50Nm	100Nm	200Nm	500Nm	1000Nm	2000Nm	5000Nm	10000Nm
Power su	upply		DC24V±15%															
Consump	tion current	100mA or less 150mA or less									less	ess 160mA or less						
Output ra	ange		±5V DC Load resistance must be more than 2k															
Bandwid	th	1kHz																
Rotation	signal		4 pulses per 1 rotation Open collector Max. ratings 30V DC, 10mA															
Safe ove	rload									;	500%FS							
Non-linea	arity									0.0	3%FS (Ty	p)						
Hysteres	is									0.0	3%FS (Ty	p)						
Repeatal	bility									0.0	3%FS (Ty	p)						
Operatio	n temp. range									-1	0 to +50	C						
Temp. ef	fect on zero									0.01%	%FS/℃ (T	yp)						
Temp. ef	fect on span									0.01%	%FS/℃ (T	/p)						
Max. rota	ation speed			25	5000rpm					2000	0rpm	15000rpm	12000rpm	10000rpm	7000rpm	6000rpm	5000rpm	4000rpm
Dimensio WxHxD	on (case size) mm		54	4×50×40				57×5	5×40	70×6	8×51	67×74×57	67×79×62	67×79×72	86×103×98	86×119×111	97×141×137	103×166×162
Total len	gth mm		74			84		9	7	150	170	177	187	217	286	306	387	447
Shaft dia	meter mm		φ5			φ8		φ	12	φ	20	φ25	φ30	φ40	φ60	φ70	φ90	φ110
Approx. Weight 160g 180g				27	0g	70	0g	1.1kg	1.5kg	2.6kg	7.3kg	10.5kg	21.4kg	36kg				
	Rotary encoder	0	0	0	0	0	0	0	0	0	O ^{@2}							
Option	Key groove							0	0	0	0	0	0	0	0	0	0	0
	Square drive											O ^{®1}		O**1				
CE mark	CE marking certification EMC directives EN61326-2-3																	

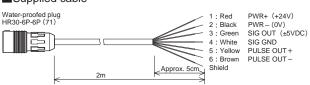
%1 : Rotary Encoder option is available %2 : Square drive option is available

External dimension

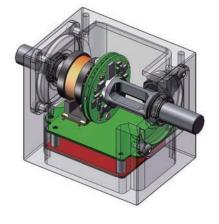


Measurement range	Α	В	С	D	E	F	G	Н	ı	J	К	L	М	N	0	Р															
0.05																															
0.1				5h7				5h7			10		10	74																	
0.2						4.0						_,			33																
0.5	0.5		32		45	18	32.3		40			54			33	50															
1	25	8.3		8h7	45			8h7	40	MO Davida O	15		15	84																	
2	i i									M3 Depth 6																					
5			34	12h7	1	19.5		12h7			20 57	E-7	20	97	35.5	55															
10			34	12117				12117			20	57	20	97	35.5																
20		31.5 6.8	13	43	13	20h7	58			20h7	51]	40	70	40	150	42.5	68													
50	21 5		43	20117	56			20117	51		50	/0	50	170	42.5	00															
100	31.5		6.8	6.8	6.8	6.8	6.8	6.8	6.8	6.8	6.8	6.8	6.8	6.8	6.8	6.8	6.8	6.8	48	25h7	54 20.5	20.5	30.8	25h7	57		55		55	177	45.5
200			54	30h7	52	1		30h7	62	M4 Depth 8	60	67	60	187	48 79																
500	21.5		64	40h7	52			40h7	72		75	75	75	217	43	79															
1000	0.5		86	60h7	66		00.0	60h7	98	ME Double 40	100	00	100	286	54	103															
2000		5.3	100	70h7	69	28.5	29.3	70h7	111	M5 Depth 10	110	86	110	306	61.5	119															
5000	25	4.0	124	90h7	72	1	28.8	90h7	137	M6 Depth 12	145	97	145	387	72.5	141															
10000		4.8	144	110h7	76	36.5	20.0	110h7	162	M8 Depth 16	172	103	172	447	85	166															

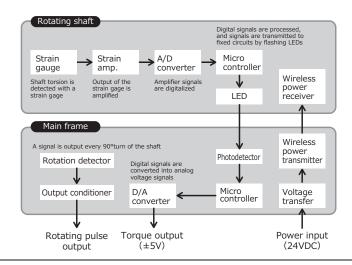
■Supplied cable



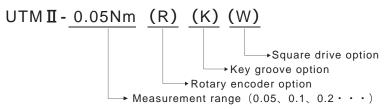
Block diagram



 $\mathsf{UTM}\, \mathbb{I}\,$ adopts strain gauges for detecting torsional strain, which is converted into an electric signal by a strain amplifier fixed on the rotating shaft. Electric power for the rotary electronics is supplied continuously through a wireless power system originally developed by UNIPULSE. The detected torque signal is converted into a digital signal, and it is transmitted to the main-frame electronics via a light signal. The rotating shaft is suspended with only two small bearings, resulting in very low rotational friction.



Structure of product code



* You can add both rotary encoder and key grove options to 5Nm, 10Nm, 20Nm and 50Nm capacity type. Model numbers are UTM II-5Nm(RK), UTM II-10Nm(RK), UTM II-20Nm(RK) and UTM II-50Nm(RK) respectively.

(R) Rotary encoder option: 0.05 to 50Nm



 Torque signal (analog ±5V) and rotation angle signals (A, B and Z photo coupler outputs) are outputted.



Optical encoder

2000C/T: 0.05 to 10Nm 1440C/T: 20Nm, 50Nm

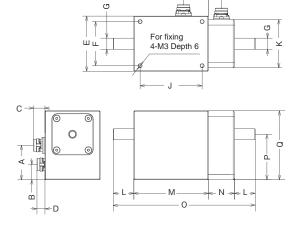
- Suitable for measurement of torque against angular variation
- * Maximum rotation speed 4500rpm : 0.05 to 10Nm 2000rpm : 20Nm, 50Nm

Installation

Fix the main unit loosely to prevent angular error induced by rotation of the main unit.



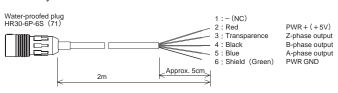
■ UTM II -0.05Nm (R) to 50Nm (R)



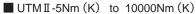
Measurement range	Α	В	С	D	Е	F	G	Н	-1	J	К	L	М	N	0	Р	Q			
0.05																				
0.1				6.8		32	φ5h7				35	10			93	- 33	50			
0.2		11						18					54							
0.5	25		- 11	0 2	8.3		40	32		10	9.5	45	55		34	19		00	30	
1	23		0.0	5.8			φ8h7		3.5	10		15		15	103					
2																				
5		40.5	40.5	40.5	40.5					φ12h7	19.5			27	20	57		116	25.5	55
10		13.5		6.8		34	φιζηί	19.5			37	20	5/		116	35.5	55			
20	31.5 1		6.8	8.5	E4	12	φ20h7	20.5	.5 7	7 58	51	40	70	47	167	42.5	68			
50		13		0.5	51	43		20.5				50	70	17	187	42.5	08			

Unit mm

Rotary encoder attached cable



(K) Key groove option: 5 to 10000Nm





Measurement range	А	В	С	D	Е	F	G	н
5	4 +0	4h9 +0 -0.03	14 +0	4 -0.012	2	14 +0.3	2.5 +0.1	_
10	-0.03	4115 -0.03	14 -0.18	4 -0.042	_	+0.1	2.0 _0	
20	6 +0 -0.03	6h9 +0	32 +0 -0.25	6 -0.012		32 +0.3 +0.1	3.5 +0.1	
50		on9 _0.03	38 +0 -0.25	0 -0.042		38 +0.3	J.J _0	M3
100	7 +0 -0.036	8h9 +0	48 +0 -025	8 -0.015	3	48 +0.3 +0.1	4 +0.2	
200	/ -0.036	8n9 _ _{0.036}	53 +0 -0.25	0 -0.051		53 +0.3	4 _0	
500	8 +0 -0.09	12h9 ⁺⁰ _{-0.043}	62 +0 -03	12 -0.018	4	62 +0.3	5 +0.2	M5
1000	11 +0	18h9 ⁺⁰ _{-0.043}	90 +0	18 -0.018 -0.061		90 +0.3	7 +0.2	M6
2000	12 +0	20h9 ⁺⁰ _{-0.052}	100 +0 -0.35	20 -0.022	_	100 +0.3	7.5 +0.2	M8
5000	14 +0	25h9 ⁺⁰ _{-0.052}	135 +0 -0.4	25 -0.022	5	135 +0.3	9 +0.2	IVIO
10000	18 +0	32h9 ⁺⁰ _{-0.062}	162 +0 -0.4	32 -0.026		162 ^{+0.5} _{+0.1}	11 +0.3	M10

(W) Square drive option: 50/100/500Nm



C € R €HS

Contactless torque detection enables stable measurement without missing data.

It is ideal to monitor torque of nut runners (fastening tools). With the high accuracy and high-speed response of UTM $\rm I\!I$, torque fluctuation can be monitored while tightening nuts.

* Note: Please do not use it with impact wrenches.

Specifications

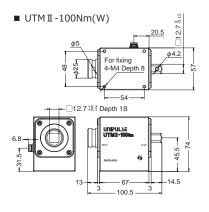
■ UTMI(W)

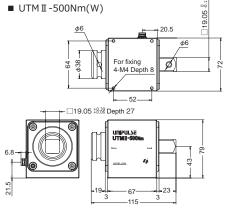
Model	UTMII-100Nm(W)	UTMII-500Nm(W)						
Measurement range	±100Nm	±500Nm						
Power supply	DC24V ±15%							
Power consumption	150mA or less							
Output range	±5V DC Load resistance	e must be more than 2k						
Bandwidth	1k	Hz						
Rotation signal	4 pulses pe	er 1 rotation						
	Open collector Max	. ratings 30V, 10mA						
Safe overload	500	%FS						
Non-linearity	0.03%F	S (Typ)						
Hysteresis	0.03%FS (Typ)							
Repeatability	0.03%FS (Typ)							
Operation temp . range	−10 to +50°C							
Temp. effect on ZERO	0.01%FS/°C (Typ)							
Temp. effect on span	0.01%FS	/°C (Typ)						
Max. rotation speed	15000rpm	10000rpm						
Torsional spring constant	38.5×103 Nm/rad	265×103 Nm/rad						
Maximum torsional angle	2.60×10 ⁻³ rad(0.149°)	1.88×10 ⁻³ rad(0.108°)						
Inertia moment	3.8×10 ⁻⁵ kgm ²	2.15×10 ⁻⁴ kgm ²						
Case size	67(W)×74(H)×57(D)mm	67 (W) ×79 (H) ×72 (D) mm						
Total length	100.5mm	115mm						
Shaft diameter	12.7mm	19.05mm						
Weight	Approx. 0.8kg	Approx. 1.4kg						
CE marking certification	EMC directives EN61326-2-3							

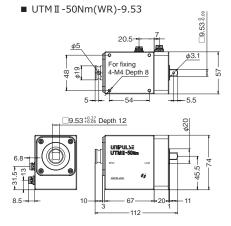
■ UTM II (WR)

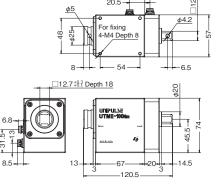
Model	UTMII-50Nm(WR)-9.53	UTMII-100Nm(WR)-12.7	UTMII-100Nm(WR)-19.05	UTMII-500Nm (WR)-19.05							
Measurement range	±50Nm	±100Nm	±100Nm	±500Nm							
Power supply	DC24V ±15%										
Power consumption	150mA or less										
Output range	±	±5V DC Load resistance must be more than 2k									
Bandwidth		1k	Hz								
Rotation signal		4 pulses pe	er 1 rotation								
		Open collector Max	. ratings 30V, 10mA								
Angle of rotation (encoder) output		3600 pulses	per rotation								
Safe overload	500%FS										
Non-linearity	0.03%FS(Typ)										
Hysteresis	0.03%FS(Typ)										
Repeatability		0.03%F	S(Typ)								
Operation temp . range	−10 to +50°C										
Temp. effect on ZERO		0.01%FS									
Temp. effect on span		0.01%FS	/°C (Typ)								
Max. rotation speed		1000	0rpm								
(Measurable range for angle)		(2000									
Torsional spring constant	17.6×10 ³ Nm/rad	26.4×10 ³ Nm/rad	54.6×10 ³ Nm/rad	136×10 ³ Nm/rad							
Maximum torsional angle	2.84×10 ⁻³ rad (0.163°)	3.78×10 ⁻³ rad (0.217°)	1.83×10 ⁻³ rad (0.105°)	3.68×10 ⁻³ rad (0.211°)							
Inertia moment	3.33×10 ⁻⁵ kgm ²	3.58×10 ⁻⁵ kgm ²	1.92×10 ⁻⁴ kgm ²	2.06×10 ⁻⁴ kgm ²							
Case size	87 (W) x74 (H) x57 (D) mm 87 (W) x79 (H) x72 (D) mm										
Total length	112mm 120.5mm 133mm										
Shaft diameter	9.53mm	12.7mm	19.05	mm							
Weight	Approx. 0.8kg	Approx. 0.9kg	Approx. 1.7kg	Approx. 1.8kg							
CE marking certification EMC directives EN61326-2-3											

External dimension

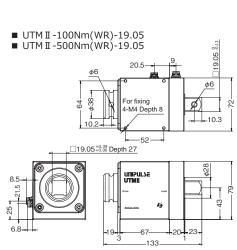








■ UTM II -100Nm(WR)-12.7



Unit mm