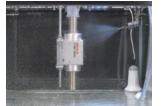
# UTTWV DRIP & RUST PROOF TYPE ROTATING TORQUE METER



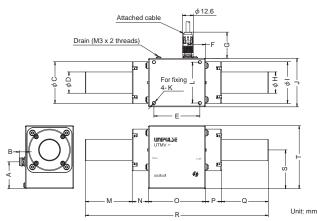
# Drip-proof type with high safe overload rating for use in harsh conditions



- Degree of protection: equivalent to IP65
  Made of rust-resistant stainless steel
  Labyrinth seal (standard)
  - With the protection against rain and seawater, it can be used outside for wind and water turbine and so on.
- PTFE rotary seal: option (S) It can be used in environment with dust and/or oil mist as well.
- Key groove: option (K)

Specifications																								
Measurement range	±0.1	Nm	±0.5	Nm	±11	Nm	±5	Nm	+10	Nm	+50	Nm	+10	0 Nm	+50	0 Nm	±100	0 Nm	+500	0 Nm				
Seal structure	ST	(S)	ST	(S)	ST	(S)	ST	(S)	ST	(S)	ST	(S)	ST	(S)	ST	(S)	ST	(S)	ST	(S)				
Power supply		(-)	_	(-)	_	(-)		(-)		DC 24	V±15%	. ,	_	(-)	_	(-)	_	(-)	_	(-)				
Consumption current					100 r	nA or le	ss						150	mA or le	ess			160 m	A or les	s				
Output range							±	5V L	oad resi	stance	must be	e more t	han 2 k											
Responsivity										1 k	Hz													
Rotation signal						4 p	oulses p	er 1 rot	ation (	Open co	llector	Max. ra	tings 30	) V, 10 r	nА									
Safe overload	500% FS																							
Non-linearity	0.03% FS or less																							
Hysteresis	0.03% FS or less																							
Repeatability	0.03% FS or less																							
Operation temp. range	-10 to +50°C																							
Temp. effect on zero	0.01% FS/°C or below																							
Temp. effect on span									0.0	1% FS/	C or be	low			_				_					
Max. rotation speed (rpm)	10000	2120	10000	1590	10000	1590	9000	1060	9000	1060	5700	680	4800	570	4800	380	4800	270	4000	180				
Torsional spring constant (Nm/rad)	11.	13	89	.5	17	2	89	97	14	00	68	87	16.4	4×10 <sup>3</sup>	93.6	i×10 <sup>3</sup>	326>	<10 <sup>3</sup>	1418	8×10 <sup>3</sup>				
Maximum torsional angle (rad)	8.99» (0.5		5.59x (0.3		5.83» (0.3		5.58x (0.3	×10 <sup>-3</sup> 20°)		×10 <sup>-3</sup> 09°)	-	×10 <sup>-3</sup> 16°)		×10 <sup>-3</sup> 350°)		×10 <sup>-3</sup> 806°)	3.07x (0.1			3×10 <sup>-3</sup> 202°)				
Inertia moment (kgm <sup>2</sup> )	1.15 ×10 <sup>-6</sup>	0.99 ×10 <sup>-6</sup>	2.19 ×10 <sup>-6</sup>	1.90 ×10 <sup>-6</sup>	2.22 ×10 <sup>-6</sup>	1.93 ×10 <sup>-6</sup>	5.60 ×10 <sup>-6</sup>	4.90 ×10 <sup>-6</sup>	5.70 ×10 <sup>-6</sup>	5.00 ×10 <sup>-6</sup>	4.21 ×10 <sup>-5</sup>	3.86 ×10 <sup>-5</sup>	9.6 ×10 <sup>-5</sup>	10.9 ×10 <sup>-5</sup>	6.2 ×10 <sup>-4</sup>	6.1 ×10 <sup>-4</sup>	3.56 ×10 <sup>-3</sup>	3.51 ×10 <sup>-3</sup>	2.38 ×10 <sup>-2</sup>	2.34 ×10 <sup>-2</sup>				
Approx. weight	390	) g	430	) g	430	) g	58	0 g	58	0 g	1.6	i kg	2.	1 kg	4.0	) kg	111	g	28 kg					
Attached cable			. 6	-condu	ctor flex	ible cab	le (2 m)	Cable	end: 7 v	vires	Cable I	length is	switch	able to !	5 m (Op	tion: U	ГМ II -L5	)						
Accesories	CATM51: 6-conductor flexible cable (5 m) Cable end: 7 wires CATM12: 6-conductor flexible cable (10 m) Cable end: 7 wires																							
CE marking certification	EMC directives EN61326-1, EN61326-2-3																							
															(S	T: Stand	ard, (S):	PTFE ro	otary sea	l optior				

## Dimension



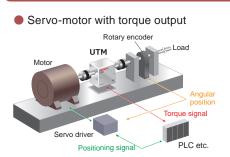
Model UTMV-0.1Nm UTMV-0.1Nm(S) UTMV-0.5Nm UTMV-0.5Nm(S) UTMV-1Nm UTMV-1Nm(S) UTMV-5Nm UTMV-5Nm(K) UTMV-5Nm(S) UTMV-5Nm(SK) UTMV-10Nm UTMV-10Nm(K) UTMV-10Nm(S) UTMV-10Nm(SK) UTMV-50Nm UTMV-50Nm(K) UTMV-50Nm(S) UTMV-50Nm(SK)

Model UTMV-100Nm UTMV-100Nm(K) UTMV-100Nm(S) UTMV-100Nm(SK) UTMV-500Nm UTMV-500Nm(K) UTMV-500Nm(S) UTMV-500Nm(SK) UTMV-1000Nm UTMV-1000Nm(K) UTMV-1000Nm(S) UTMV-1000Nm(SK) UTMV-5000Nm UTMV-5000Nm(K) UTMV-5000Nm(S) UTMV-5000Nm(SK)

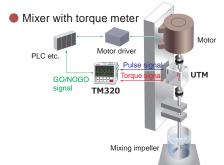
Measurement range	Α	В	φC	φD	E	F	G	φH	φI	J	K	L	М	N	0	Р	Q	R	S	Т	Key groove
0.1 Nm	25	8.3	24	5h7	45	18	32.3	5h7	24	40	M3 Depth 6	32	10	11.5	54	11.5	10	97	33	50	-
0.5 Nm	25	8.3	26	8h7	45	18	32.3	8h7	26	40	M3 Depth 6	32	15	11.5	54	11.5	15	107	33	50	-
1 Nm	25	8.3	26	8h7	45	18	32.3	8h7	26	40	M3 Depth 6	32	15	11.5	54	11.5	15	107	33	50	-
5 Nm	25	8.3	30.5	12h7	45	19.5	32.3	12h7	30.5	40	M3 Depth 6	34	20	12	57	12	20	121	35.5	55	
10 Nm	25	8.3	30.5	12h7	45	19.5	32.3	12h7	30.5	40	M3 Depth 6	34	20	12	57	12	20	121	35.5	55	
50 Nm	31.5	6.8	43.4	20h7	58	20.5	30.8	20h7	43.4	51	M3 Depth 6	43	50	18.5	70	18.5	50	207	42.5	68	
100 Nm	31.5	6.8	49	25h7	54	20.5	30.8	25h7	49	57	M4 Depth 8	48	55	19	67	19	55	215	45.5	74	Refer to Page 12
500 Nm	21.5	6.8	64.2	40h7	52	20.5	30.8	40h7	64.2	72	M4 Depth 8	64	75	20	67	20	75	257	43	79	
1000 Nm	25	5.3	86.6	60h7	66	28.5	29.3	60h7	86.6	98	M5 Depth 10	86	100	20	86	20	100	326	54	103	
5000 Nm	25	4.8	124.6	90h7	72	28.5	28.8	90h7	124.6	137	M6 Depth 12	124	145	23	97	23	145	433	72.5	141	

\* Dimension of rotary seal type is same as standard type





By setting UTM between the rotary encoder and motor, you can make a servo motor system with torque output. The system can be applied to various applications, such as robot hands or other systems which can detect load.



The system measures torque on the axis of mixing impellers. The change of viscosity can be detected by monitoring torque.

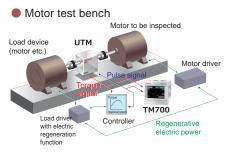
By using torque monitor (TM320 etc.), I/O signals can be controlled by the threshold levels.

Measurement of torque required to rotate feed rollers



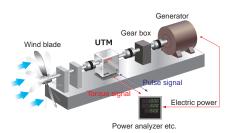
Torque fluctuation can be monitored while a sheet of paper or film is fed by the drive roller. With torque measurement, quantitative management and maintenance of feed roller are possible





Mechanical power can be calculated from torque and rotational speed. Also, by applying energy recovery system, the test apparatus will be eco-friendly (energy-saving).

### Power generation efficiency test



The efficiency of wind turbine generator and so on can be tested. Power can be estimated based on torque and rotational speed measured with UTM, and power generation efficiency can be calculated by comparing power and generated energy.

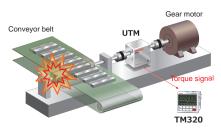


By measuring the torque required to rotate automotive parts such as steering unit, it is possible to quantize the smoothness of the rotation for standardization of the quality inspection

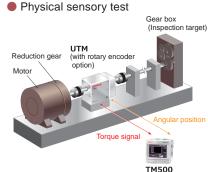
Engine test bench Engine UTM Load device (motor etc.) TM700 Controller

In case of torque measurement with large vibration, such as measurement of engines, please attach double disk coupling and use double bearing.

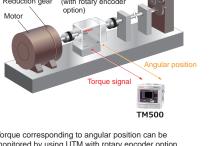
### Fault detection of conveyor belt



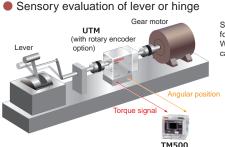
By monitoring the motor shaft torgue of a conveyor belt. faults and conveyor-related hazards can be detected (e.g. materials get caught to conveyor system). Conveyor belts will be stopped immediately after faults like contamination and overturning of products are detected.



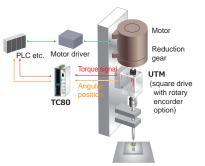
The system can be applied to automation of physical sensorv test



Torque corresponding to angular position can be monitored by using UTM with rotary encoder option

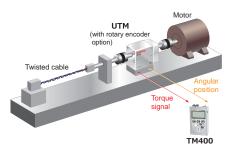


Relationship between torque and angle/displacement (distance) Screw driver with torque monitoring



Torque can be measured in the process of tightening screws. Since the torque can be controlled during the whole process, the system can be applied to automation of process

Torsion testing machine



Stiffness and performance of wire or cable can be tested by checking torque applied by a torsion test machine with ÚTM.

Smoothness of lever, hinge, and so on can be quantized for quality control purpose.

With a optional rotary encoder, torque-angle relationship can be monitored.



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